

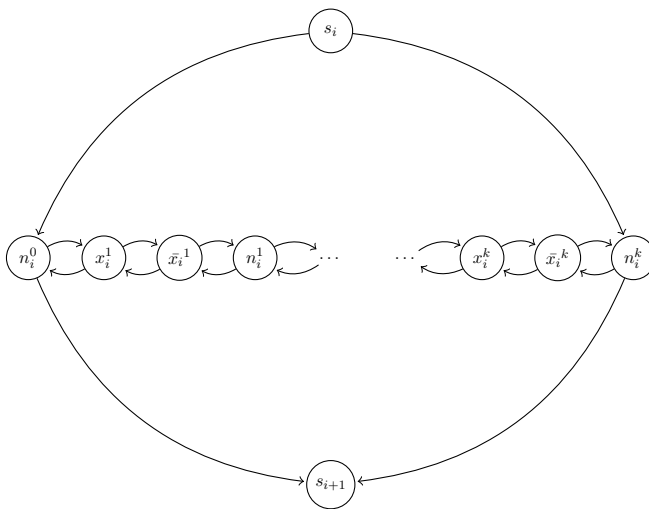
# 1 Reducing from CNF-SAT to HAMPATH

A path from  $s$  to  $t$  in a graph  $G$  is hamiltonian when the path goes through all nodes exactly once. The *HAMPATH* problem is defined as:

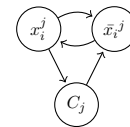
$$HAMPATH = \{(G, s, t) \mid \text{there exists an hamiltonian path in the oriented graph } G \text{ from } s \text{ to } t\}$$

**Question 1.** Show that *HAMPATH* is  $\mathcal{NP}$ -complete.

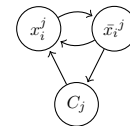
*Suggestion: start from a CNF-SAT formula with  $k$  clauses and  $l$  variables. Build a graph with (for  $i$  a variable and  $j$  a clause): 3 nodes  $x_i^j, \bar{x}_i^j$  et  $n_j^i$ ; 2 nœuds  $s_i$  and  $n_i^0$ ; 1 node  $C_j$  plus one node  $s_{i+1}$  using the following gadgets:*



(a) Variable gadget



(b) Gadget for  $x_i$  used in  $C_j$



(c) Gadget for  $\bar{x}_i$  used in  $C_j$

**Question 2.** Show that the *HAMPATH* problem stays  $\mathcal{NP}$ -complete if we remove the orientedness of the graphs considered.

## 2 Time hierarchy theorem

In this section, we will consider 2-tape deterministic Turing machines. We select a coding  $\langle M \rangle$  for the Turing machine  $M$ . For instance,  $\langle M \rangle$  codes the states with words of  $\{0, 1\}^*$ , the tape alphabet with words of  $\{\alpha, \beta\}^*$ , heads direction with  $\{<, >, -\}^2$ . A TM is then represented with a sequence of transitions for each state. For the state  $e$ , we represent it as  $e|a_1, b_1, c_1, d_1, e_1, f_1, \dots, a_k, b_k, c_k, d_k, e_k, f_k|$  where the  $e, (e_i)_i$  are the states, the  $(a_i)_i, (b_i)_i, (c_i)_i, (d_i)_i$  are all words in both tape and the  $(f_i)_i$  are the directions.  $a$  (resp.  $b$ ) is the letter read on the first tape (resp. second tape) during the transition and  $c$  (resp.  $d$ ) is the letter written on the first tape (resp. second tape).

**Définition 1.** The set  $TIME(f(n))$  corresponds to the set of problems for which there exists a Turing machine deciding them in less than  $f(n)$  computing steps over inputs of size  $n$ .

In the same manner that we say that sorting can be done in  $O(n \times \ln(n))$  (and thus omitting to say “when the input has size  $n$ ”, we always write  $TIME(f(n))$  but this should be read as  $TIME(n \rightarrow f(n))$  because the  $n$  represents the size of the input.

In the remaining part of the TD, when needed, you can use the linear speedup theorem stating that for all  $g$  and all  $\epsilon > 0$  fixed, we have  $TIME(g(n)) \subseteq TIME(n + 2 + \epsilon g(n))$ .

**Définition 2.** A function  $f$  is time constructible when there exists a machine  $M$  taking  $1^n$  as input and producing  $f(n)$  in time  $f(n)$ .

The time hierarchy theorem states that when  $f$  is a time constructible function then:

$$TIME\left(o\left(\frac{f(n)}{\log f(n)}\right)\right) \subsetneq TIME(f(n))$$

We will demonstrate here a lighter version of the theorem:  $TIME(f(n)) \subsetneq TIME(f(2n+1)^3)$  with  $n^3 \leq f(n)$ . For  $f$  time constructible, we define  $Halt_f = \{\langle M \rangle \# x \mid M \text{ accepts } x \text{ in } f(|x|) \text{ steps}\}$ .

**Question 3.** Justify that  $Halt_f \in TIME(f(n)^3)$ .

Let us suppose that  $Halt_f \in TIME\left(\frac{f(\lfloor n/2 \rfloor)}{2}\right)$ . Let  $K$  be a TM deciding  $Halt_f$  in time  $f(\lfloor n/2 \rfloor)/2$ , we can build  $D_K$  taking  $\langle M \rangle$  as input and running  $K$  on  $\langle M \rangle \# \langle M \rangle$ .  $D_K$  accepts when  $K$  refuses and refuses when  $K$  accepts.

**Question 4.** Justify that  $D_K$  can be built such that  $D_K \in TIME(f(n))$ .

**Question 5.** Justify that  $D_K$  can not exist using a diagonalization argument.

**Question 6.** Conclude that  $TIME(f(\lfloor n/2 \rfloor)/2) \subsetneq TIME(f(n)^3)$ .

**Question 7.** Show that  $P \subsetneq EXPTIME \subsetneq 2-EXPTIME$ .

We recall:  $P = \bigcup_{k \in \mathbb{N}} TIME(n^k)$ ,  $EXPTIME = \bigcup_{k \in \mathbb{N}} TIME(2^{n^k})$ ,  $2-EXPTIME = \bigcup_{k \in \mathbb{N}} TIME(2^{2^{n^k}})$

### 3 An EXPTIME-complete problem

**Question 8.** Justify that  $f(x) = 2^x$  is time constructible and show that  $Halt_f \in EXPTIME$ .

**Question 9.** Let  $L \in EXPTIME$ , show that  $L$  is polynomial time reducible to  $Halt_f$  and thus prove that  $Halt_f$  is EXPTIME-complete.

### 4 A PSPACE-complete problem

The set of Quantified Boolean Formulæ (QBF) is defined by induction as:

- all propositional variables are QBF;
- if  $\phi$  is QBF then  $\neg\phi$  also is QBF;
- if  $\phi$  and  $\psi$  are QBF then  $\phi \wedge \psi$  is QBF
- if  $\phi$  is QBF and  $p$  is a propositional variable then  $\forall p\phi$  and  $\exists p\phi$  are QBF

QBF are equipped with their usual Boolean valuation. The language of  $TQBF$  is the language of QBF evaluating to true.

**Question 10.** Show that  $TBQF$  is PSPACE-complete.

Suggestion for PSPACE hardness: start from  $L \in PSPACE$ . Show that  $L$  is decided by  $K$  for which it exists  $P \in \mathbb{N}[X]$  such that on an input of size  $n$ ,  $K$  decides in time  $2^{P(n)}$  and space  $P(n)$ . Reduce  $L$  to  $TQBF$ . Encode the state of  $K$  and its memory with a  $P(n)$  uplet of  $\{0, 1\}$  and build a formula  $\Phi(c_1, c_2, t)$  describing whether  $K$  can move from the state  $c_1$  to  $c_2$  in time  $2^t$  (use a fast exponentiation).